GNSS Anti-jam RF-to-RF On Board Unit for ERTMS Train Control

Cosimo Stallo¹, Pietro Salvatori¹, Andrea Coluccia¹, Alessandro Neri¹, Francesco Rispoli¹, Massimiliano Ciaffi²

¹ RadioLabs ² RFI

Outline



- ERTMS and Virtual Balise Concept
- Characterization of GNSS performance
- Jamming issue and anti-jamming filter design guidelines
- Performance analysis
- Conclusions

Research Consortiun

Radiolabs is involved on major international research projects with ESA, ASI, GSA and Centers of Excellence

Connectivity Bearer-independent applications 3/4/5G – Satellite Software Defined Networks

GEO Localization

High Integrity applications Multi-constellation, dual frequency Multi sensors

Security

Network security protocols Resilient GNSS signal processing

Leader on scientific research for safety-critical geo-localization









Hitachi Rail SpA



Critical issue: Intentional Interferences (jamming, spoofing and meaconing)





Ref. DB4Rail project ESA

Introduction



Possible GNSS interferences must be analysed and mitigated to ensure the ERTMS can operate with GNSS positioning without degradations:



GNSS Automated Virtualized Test Environment for Rail (GATE4Rail) deals with tasks TD2.4 and TD2.6 of the Shift2Rail Multi Annual Action Plan. Particularly, its main goals are: i) achieving a realistic characterization of the environment in terms of railway and GNSS infrastrustructures able to evaluate the performances and properties of some fail-safe train positioning components in nominal and fault conditions; ii) defining a common test process framework for zero on-site testing instead of testing on-site saving effort and time.

The project "Digital Beamforming for Rail" DB4RAIL aims at designing, developing and prototyping a software digital beamforming platform for antenna array coupled with advanced GNSS signal processing techniques for high rejection of GNSS interfering signals, including jamming and spoofing, to be used for supporting the evolution of the LDS based on GNSS in ERTMS/ETCS.

ERTMS/ETCS



The European standard for railway signaling is the ERTMS / ETCS (European Railway Traffic Management System / European Train Control System) is the standard for European railways.



GNSS- based Virtual Balise Concept



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Characterisation of GNSS performance



- 1. Characterization of GNSS performance
- 2. Defining a common test process framework for zero on-site testing instead of testing on-site saving effort and time;
- 3. Provide a laboratory test architecture capable of simulating railway scenarios for GNSS-based ERTMS applications;



Reference Architecture



Rac

abs

Jamming, Spoofing, Meaconing



Jamming is the transmission of signals **Spoofing** is the intentional transmission of that disturb the genuine reception: fake GNSS signals to make the receiver estimate a wrong position and/or timing Main consequences: Interference **Denial of Service** Cryptography can mitigate the spoofing Meaconing is the transmission of recorded authentic GNSS signals to make the receiver estimate a wrong position and/or timing Also cryptographically protected signals could be affected by meaconing

Processing scheme





Ref. DB4Rail project ESA

GNSS Antenna Array Design





GNSS Antenna Array Development













Anti-jamming filtering





Hystogram comparison



The jammer presence can be detected by accounting for the hystograms



Jamming Detection





The p-value testing





The jammer detector algorithm has been calibrated by using GNSS signals in absence of any jammer signals, and the following parameters have been chosen:

- Detection period = 20 ms
- Number of bins = 16
- Level of significance = 10-4.

Jamming DoA estimation and mitigation Radi



Simulation results: assumptions





Acquisition results (1)



Scenario - J/S = 20 dB, Jammer [Azimuth = 180°, Elevation = 10°]



Not acquired signals Acquired signals Acquisition Metric PRN number (no bar - SV is not in the acquisition list)

Acquisition results

Null-steering

Antenna 1

Acquisition results (2)



30

Scenario - J/S = 20 dB, Jammer [Azimuth = 180°, Elevation = 25°]



Acquisition results (3)



Scenario - J/S = 20 dB, Jammer [Azimuth = 180°, Elevation = 40°]



Acquisition results (4)



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Scenario - J/S = 20 dB, Jammer [Azimuth = 180°, Elevation = 55°]



Acquisition results (5)



Scenario - J/S = 20 dB, Jammer [Azimuth = 180°, Elevation = 70°]





Null-steering

Overall solution



The anti-jamming mitigation platform developed in the ESA GSTP 6.2 DB4Rail project can be integrated in the GATE4Rail test-bed architecture to create a **unified test-bed architecture** to test the system resilience to RF interference and jamming.



Gate4Rail Geo-Distributed Lab Concept



GATE4Rail architecture for simulating railway scenarios for GNSSbased ERTMS applications by integrating different simulation blocks and by defining their interfaces in order to cover the global simulation chain

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The GATE4Rail proposal addresses the topic S2R-OC-IP2-02-2018 - Modern methodologies and verifications for GNSS in Railways and virtual test environment.

Gate4Rail Architecture





Conclusions



- GNSS positioning for the ERTMS system needs a characterisation of RF signals including those that can be affected by interferences. Our approach is to create a unified test-bed architecture to test the system resilience to RF interference and jamming by exploiting:
 - the GNSS Anti-jam RF-to-RF On Board Unit optimized for ERTMS Train Control (DB4Rail)
 - the distributed test-facility to evaluate the GNSS performance with a zero-on-site testing approach (Gate4Rail)
- Jamming can impact primarily on the ERTMS system availability and the antenna array solution of the DB4Rail project can be used to mitigate such a threat
- GATE4Rail platform is ideal to test also the system anti-jamming capability in a controlled environment that otherwise would require severe constraints and high costs.



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www.gate4rail.eu

www.radiolabs.it